

Throughput-Optimal Topology Design for Cross-Silo Federated Learning

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Inria



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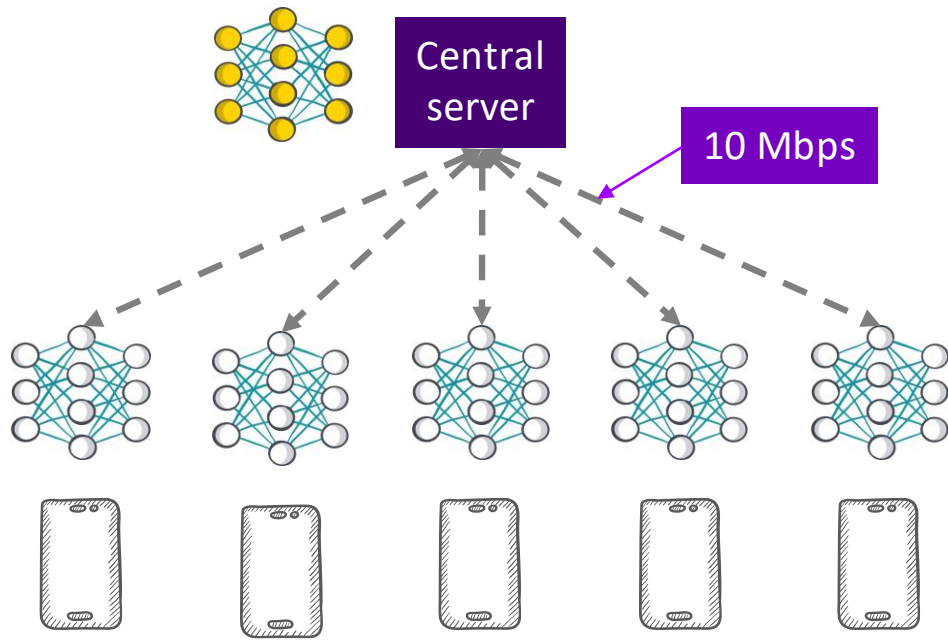
Accenture Labs

Federated Learning

Federated learning involves *“Training statistical models over remote devices or siloed data centers, such as mobile phones or hospitals, while keeping data localized”* (Li et al. 2020).

Federated Learning

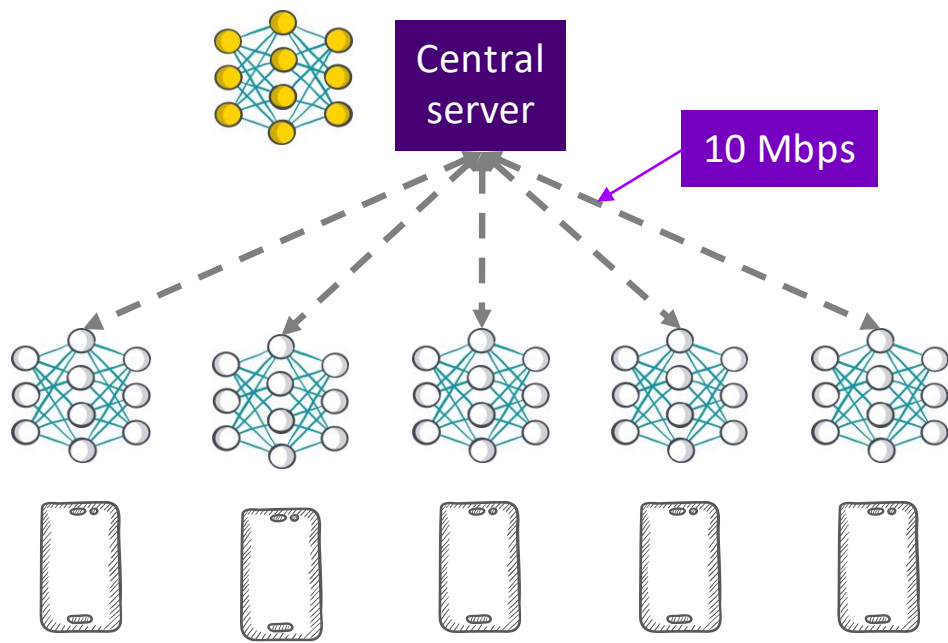
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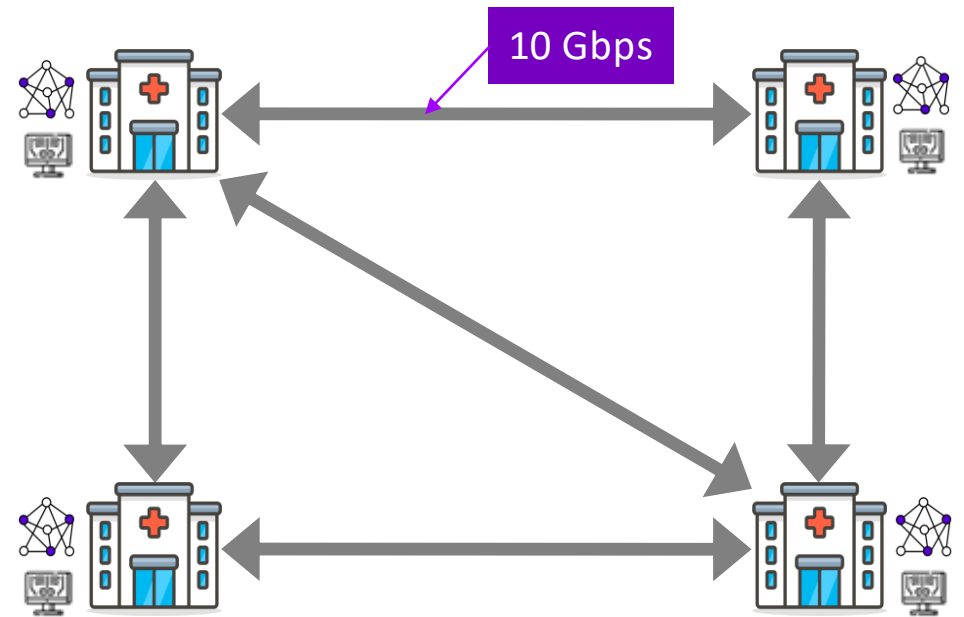
Cross-Device/Fixed STAR topology

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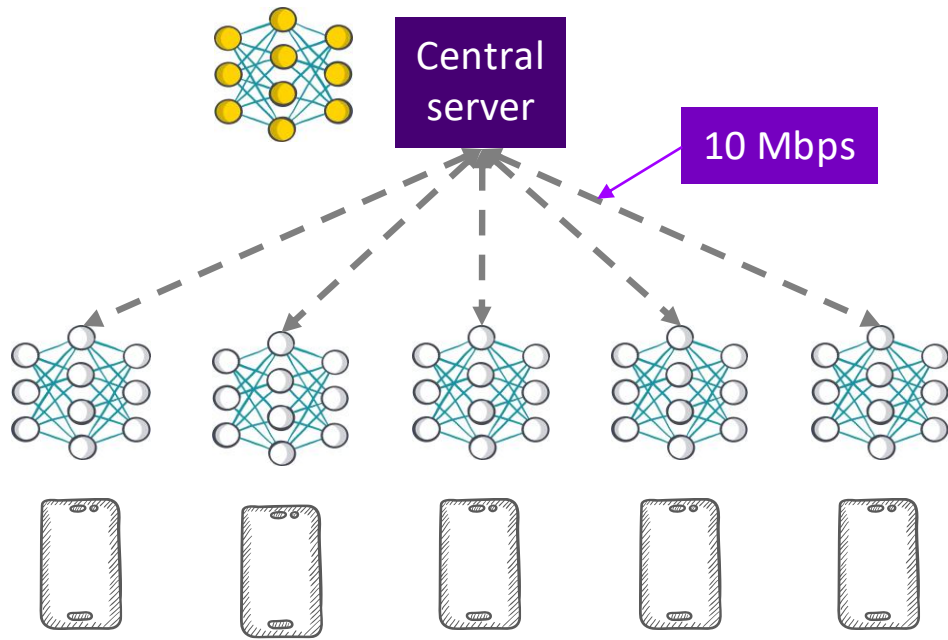
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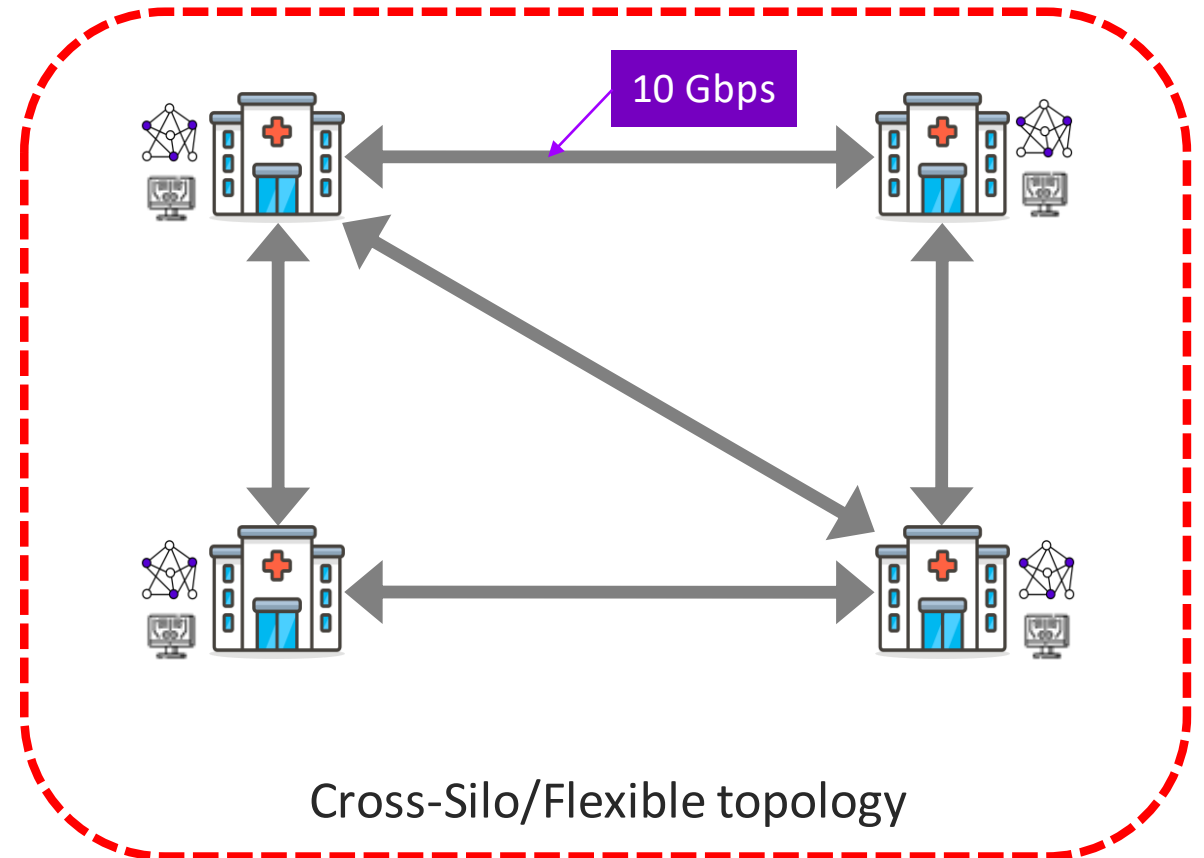
Cross-Silo/Flexible topology

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Communication Topology & Training Time

$$\textit{Training Time} = \# \textit{Iterations} \times \textit{Iteration Time}$$

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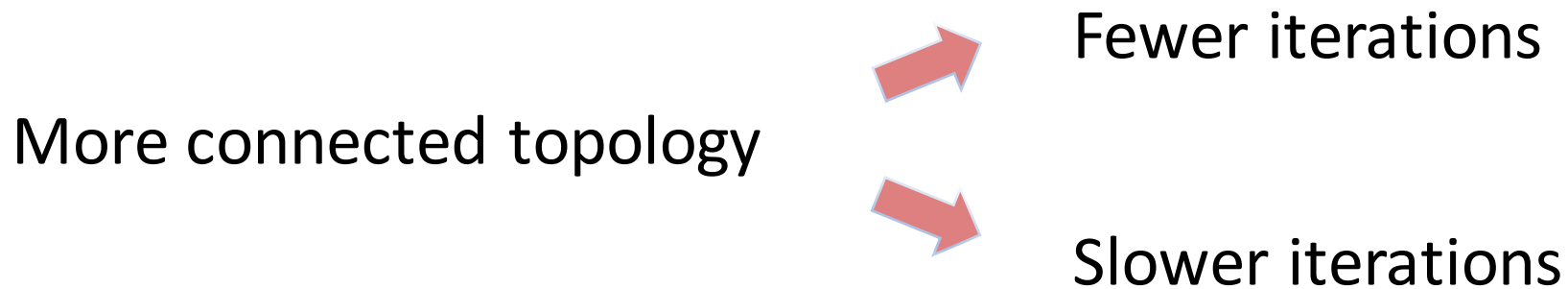


Slower iterations

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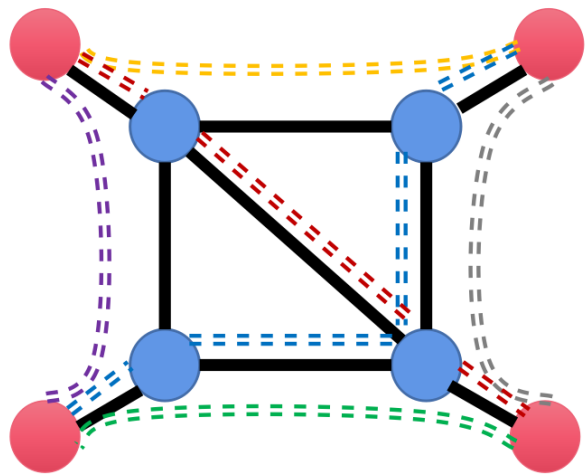
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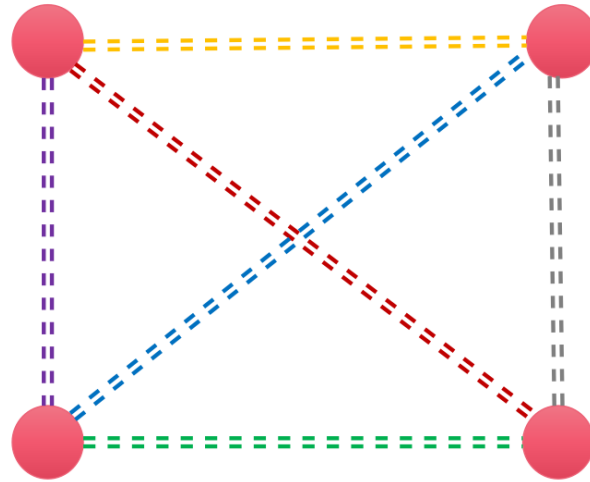
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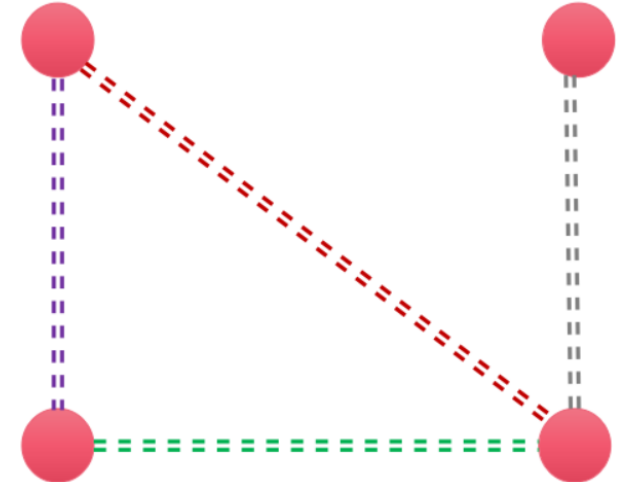
Problem Formulation



Underlay

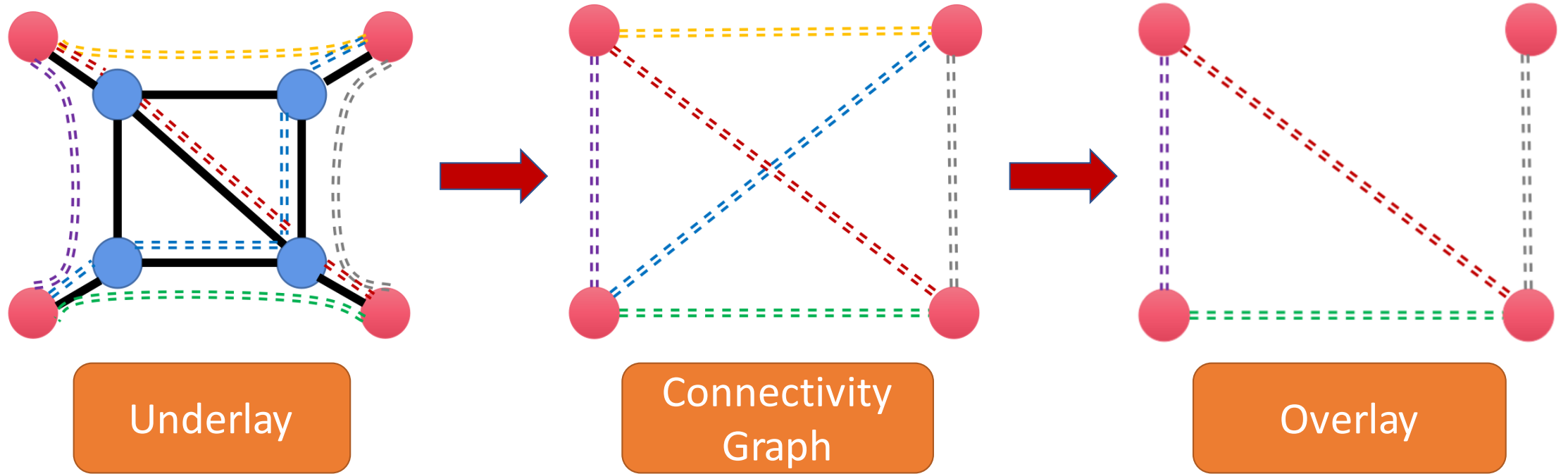


Connectivity
Graph



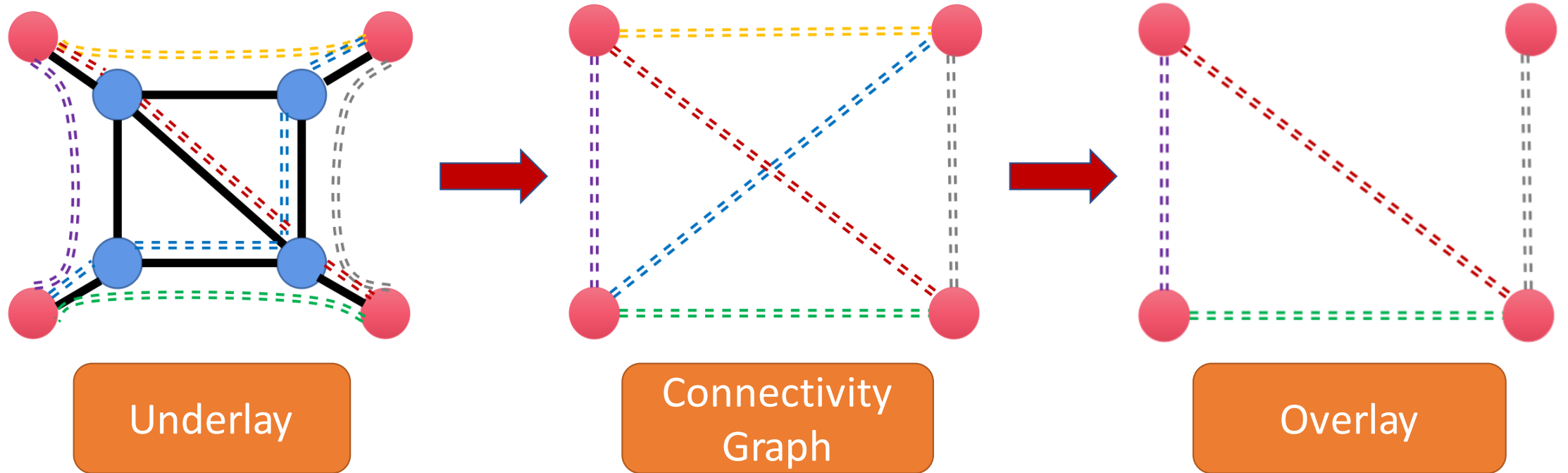
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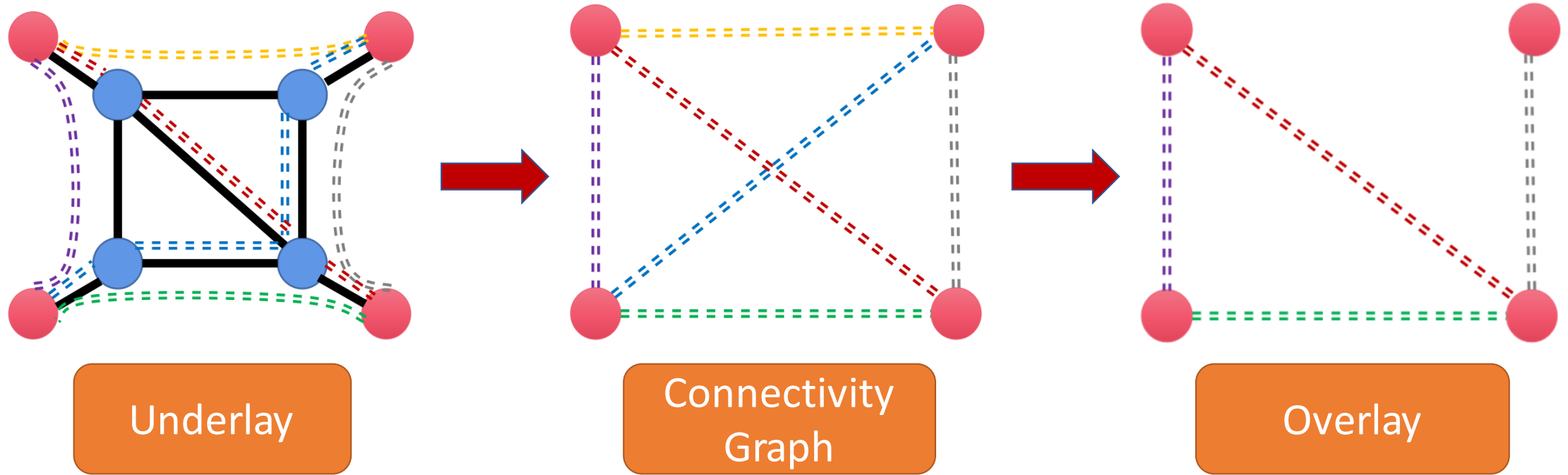
$$d_o(i, j) = s \times T_c(i) + l(i, j) + \frac{M}{\min \left(\frac{C_{UP}(i)}{|\mathcal{N}_i^-|}, \frac{C_{DN}(j)}{|\mathcal{N}_j^+|}, A(i', j') \right)}$$

Problem Formulation



$$d_o(i, j) = s \times T_c(i) + \underbrace{l(i, j)}_{\text{Latency}} + \frac{M}{\min \left(\frac{C_{UP}(i)}{|\mathcal{N}_i^-|}, \frac{C_{DN}(j)}{|\mathcal{N}_j^+|}, A(i', j') \right)}$$

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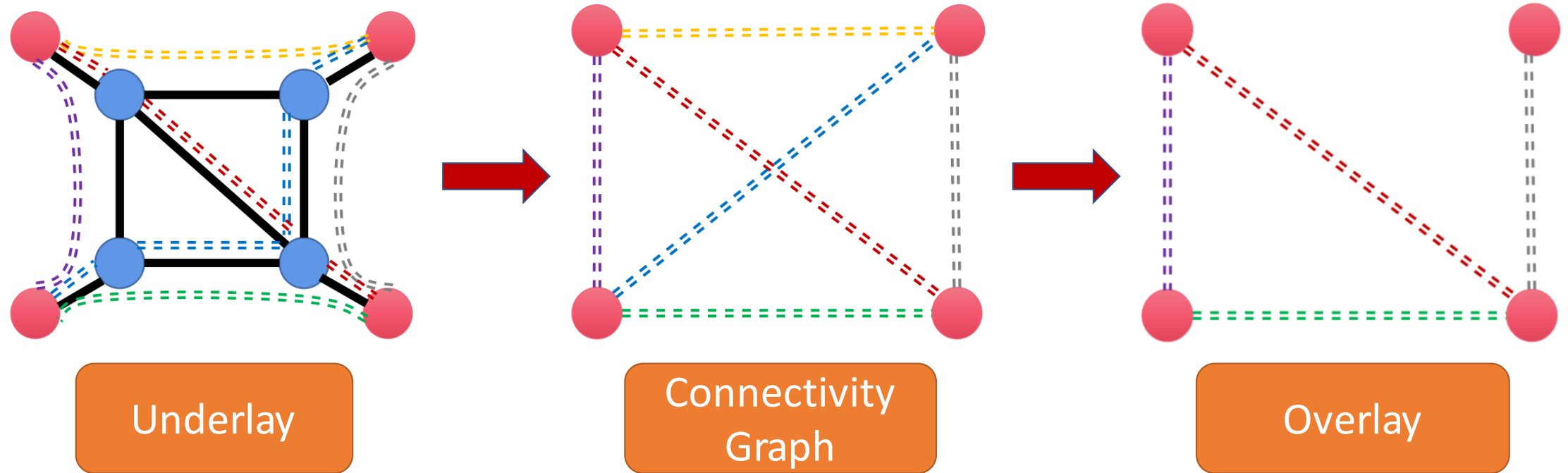


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Capacities

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Problem Formulation



$$d_o(i, j) = \underbrace{s \times T_c(i)}_{\text{Computation Time}} + \underbrace{l(i, j)}_{\text{Latency}} + \overbrace{\min \left(\frac{C_{UP}(i)}{|\mathcal{N}_i^-|}, \frac{C_{DN}(j)}{|\mathcal{N}_j^+|}, A(i', j') \right)}^{\text{Model size } M, \text{ Capacities}}$$

Problem Formulation

Each silo maintains a local copy of the model. At time $t_i(k)$ silo i starts its k -th iteration, it

- 1) updates the local model through minibatch gradient descent.
- 2) sends the new model to its out-neighbors in the overlay.
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This is a **synchronous system**. The following recurrence holds:

$$t_i(k + 1) = \max_{j \in \mathcal{N}_i^+ \cup \{i\}} (t_j(k) + d_o(i, j))$$

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Max-plus algebra & synchronization theory show that:

- τ_i does not depend on the specific silo.
- τ_i is the cycle time of the graph \mathcal{G}_o , defined as $\tau(\mathcal{G}_o) = \max_{\gamma} \frac{d_o(\gamma)}{|\gamma|}$,
where γ is a circuit of \mathcal{G}_o .

Analysis

Minimal Cycle Time (MCT)

Input: A strong directed graph $G_c = (V, E_c)$,

$$\{C_{UP}, (i)C_{DN}(j), l(i, j), A(i', j'), T_c(i), \forall (i, j) \in E_c\}$$

Output: Strong spanning subdigraph of G_c with minimal cycle time

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Table 1: Algorithms to design the overlay \mathcal{G}_o from the connectivity graph \mathcal{G}_c .

Network	Conditions	Algorithm	Complexity	Guarantees
Edge-capacitated	Undirected \mathcal{G}_o	Prim's Algorithm [80]	$\mathcal{O}(\mathcal{E}_c + \mathcal{V} \log \mathcal{V})$	Optimal solution (Prop. 3.1)
Edge/Node-capacitated	Euclidean \mathcal{G}_c	Christofides' Algorithm [69]	$\mathcal{O}(\mathcal{V} ^2 \log \mathcal{V})$	3N-approximation (Prop. 3.3,3.6)
Node-capacitated	Euclidean \mathcal{G}_c and undirected \mathcal{G}_o	Algorithm 1 (App. D)	$\mathcal{O}(\mathcal{E}_c \mathcal{V} \log \mathcal{V})$	6-approximation (Prop. 3.5)

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The proposed algorithms output either a **ring** or a **tree** with constrained degree.

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Numerical Experiments

We considered three **real topologies** from *Rocketfuel engine* (**Exodus** and **Ebone**) and from *The Internet Topology Zoo* [48] (**Géant**), and two synthetic topologies (**AWS North-America** and **Gaia**) built from the geographical locations of AWS data centers.

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Table 2: Datasets and Models. Mini-batch gradient computation time with NVIDIA Tesla P100.

Dataset	Task	Samples ($\times 10^3$)	Batch Size	Model	Parameters ($\times 10^3$)	Model Size (Mbits)	Computation Time (ms)
Shakespeare [14, 72]	Next-Character Prediction	4, 226	512	Stacked-GRU [17]	840	3.23	389.6
FEMNIST [14]	Image classification	805	128	2-layers CNN	1, 207	4.62	4.6
Sentiment140 [30]	Sentiment analysis	1, 600	512	GloVe [82]+ LSTM [37]	4, 810	18.38	9.8
iNaturalist [99]	Image classification	450	16	ResNet-18 [35]	11, 217	42.88	25.4

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Code: <https://github.com/omarfoq/communication-in-cross-silo-fl>

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Table 3: iNaturalist training over different networks. 1 Gbps core links capacities, 10 Gbps access links capacities. One local computation step ($s = 1$).

Network name	Silos	Links	Cycle time (ms)					Ring's training speed-up	
			STAR	MATCHA ⁽⁺⁾	MST	δ -MBST	RING	vs STAR	vs MATCHA ⁽⁺⁾
Gaia [36]	11	55	391	228 (228)	138	138	118	2.65	1.54 (1.54)
AWS North America [91]	22	231	288	124 (124)	90	90	81	3.41	1.47 (1.47)
Géant [27]	40	61	634	452 (106)	101	101	109	4.85	3.46 (0.81)
Exodus [64]	79	147	912	593 (142)	145	145	103	8.78	5.71 (1.37)
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Sparser topologies can lead to a faster convergence **even in the absence of congestion.**

Conclusion

- Synchronization theory & max-plus algebra to model and optimize iteration time.
- In cross-silo setting, replacing server by peer-to-peer communication, results in significant speed ups ($\times 9$).
- Counter-intuitively, sparser topologies may lead to faster convergence even in the absence of congestion.

Thank you for your attention

Code: <https://github.com/omarfoq/communication-in-cross-silo-fl>

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